

Linear Algebra, EE 10810/EECS 205004

Note 1.4 – 1.5

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- **Office Hours:**

1. RK: Every Wednesday, 1:00-5:00 PM at R 911, Delta Hall, or by appointment.
2. Raul Robles-Robles (last year PhD student); email: raulamauryrobles@hotmail.com.
3. TA time, Every Wednesday, 6:30-8:30 PM at Delta 217, or by appointment.

- **Integrity:** Next Quiz on September 30th, Wednesday, 10:10 AM - 10:30 AM.

- **Assignment:** for the Quiz on Sep. 30th

1. Solve the system of linear equations by Gaussian elimination method,

$$\begin{cases} 2x_1 - 2x_2 - 3x_3 & = -2 \\ 3x_1 - 3x_2 - 2x_3 + 5x_4 & = 7 \\ x_1 - x_2 - 2x_3 - x_4 & = -3 \end{cases} \quad (1)$$

2. Show that if

$$M_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad M_2 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \quad \text{and} \quad M_3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad (2)$$

then the *span* of $\{M_1, M_2, M_3\}$ is the set of all symmetric 2×2 matrices.

3. Show that a **subset** W of a vector space \mathcal{V} is a **subspace** of \mathcal{V} if and only if $\text{span}(W) = W$.
4. Show that if S_1 and S_2 are subsets of a vector space \mathcal{V} such that $S_1 \subseteq S_2$, then $\text{span}(S_1) \subseteq \text{span}(S_2)$.

From Scratch !!

- Show that if S_1 and S_2 are arbitrary subsets of a vector space \mathcal{V} , then $\text{span}(S_1 \cup S_2) = \text{span}(S_1) + \text{span}(S_2)$.

- Definition: A *subset* \mathcal{W} of a vector space \mathcal{V} over a field \mathcal{F} is called **subspace** of \mathcal{V} if \mathcal{W} is a vector space over \mathcal{F} under the operation of addition and scalar multiplication defined on \mathcal{V} .
- Theorem 1.3: Subspace \mathcal{W} :
 1. $\vec{0} \in \mathcal{W}$.
 2. $\vec{x} + \vec{y} \in \mathcal{W}$ whenever $\vec{x} \in \mathcal{W}$ and $\vec{y} \in \mathcal{W}$.
 3. $a\vec{x} \in \mathcal{W}$ whenever $a \in \mathcal{F}$ and $\vec{x} \in \mathcal{W}$.
- Theorem 1.4: Any intersection of subspaces of a vector space \mathcal{V} is a subspace of \mathcal{V} .
- Question: Is the Union of subspaces of a vector space \mathcal{V} also a subspace of \mathcal{V} ?

- **Systems of Linear Equations:**

$$\begin{array}{rccccrcr} a_1 & -2a_2 & & +2a_4 & -3a_5 & = & 2 \\ 2a_1 & -4a_2 & +2a_3 & & +8a_5 & = & 6 \\ a_1 & -2a_2 & +3a_3 & -3a_4 & +16a_5 & = & 8 \end{array} \quad (3)$$

- Alternative: Geometric interpretation of Systems of Linear Equations: 2D lines intersecting at a point, 3D (intersecting at a plane)

$$\begin{array}{r} x - 2y = 1, \\ 3x + 2y = 11. \end{array} \quad (4)$$

- Rules for systems of linear equations: $\overline{\overline{P}} \overline{\overline{D}} \overline{\overline{E}}$

1. Scalar Multiplication, Diagonalized Matrix, ex, $\overline{\overline{D}} = \begin{bmatrix} a & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$,

2. Elimination, Elimination Matrix, ex, $\overline{\overline{E}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -l & 0 & 1 \end{bmatrix}$

3. Row Exchange, Permutation Matrix, ex, $\overline{\overline{P}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$

- Gauss Elimination

- Pivot

- Augmented Matrix, $\overline{\overline{M}}\vec{a} = \vec{b} \Rightarrow \left[\overline{\overline{M}} \mid \vec{b} \right]$.

- Breakdown of Elimination

- Inverse Matrix, $\overline{\overline{M}}^{-1}$

- Span: $\text{span}(S)$

- Linearly Dependent and Linearly Independent

- Basis