

Linear Algebra, EE 10810/EECS 205004

Note 1.5 – 1.6

Ray-Kuang Lee¹

¹Room 911, Delta Hall, National Tsing Hua University, Hsinchu, Taiwan.

Tel: +886-3-5742439; E-mail: rkleee@ee.nthu.edu.tw

(Dated: Fall, 2020)

- **Office Hours:**

1. Raul Robles-Robles (last year PhD student); email: raulamauryrobles@hotmail.com.
2. TA time, Every Wednesday, 6:30-8:30 PM at Delta 217, or by appointment.

- **Integrity:** Next Quiz on October 7th, Wednesday, 10:10 AM - 10:30 AM.

- **Assignment:** for the Quiz on Oct. 7th

1. Determine whether the following sets are linearly dependent or linearly independent

(a)

$$\left\{ \begin{pmatrix} 1 & -3 \\ -2 & 4 \end{pmatrix}, \begin{pmatrix} -2 & 6 \\ 4 & -8 \end{pmatrix} \right\} \quad \text{in } \overline{\overline{M}}_{2 \times 2}(\mathcal{R}) \quad (1)$$

(b)

$$\left\{ \begin{pmatrix} 1 & -2 \\ -1 & 4 \end{pmatrix}, \begin{pmatrix} -1 & 1 \\ 2 & -4 \end{pmatrix} \right\} \quad \text{in } \overline{\overline{M}}_{2 \times 2}(\mathcal{R}) \quad (2)$$

(c) $\{x^3 + 2x^2, -x^2 + 3x + 1, x^3 - x^2 + 2x - 1\}$ in $P_3(\mathcal{R})$

2. Prove that, let \mathcal{V} be a vector space, and let $\mathcal{S}_1 \subseteq \mathcal{S}_2 \subseteq \mathcal{V}$. If \mathcal{S}_1 is linear dependent, then \mathcal{S}_2 is linearly dependent.
3. Prove that, a set S is linearly dependent iff $S = \{\vec{0}\}$ or there exist distinct vectors $\vec{v}, \vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$ in S s.t. \vec{v} is a linear combination of $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$.

From Scratch !!

- **Systems of Linear Equations:**

$$\begin{aligned} 2a_1 + 4a_2 - 2a_3 &= 2 \\ 4a_1 + 9a_2 - 3a_3 &= 8 \\ -2a_1 - 3a_2 + 7a_3 &= 10 \end{aligned} \quad (3)$$

- Alternative: Geometric interpretation of Systems of Linear Equations: 2D and 3D (intersections of planes)

- Matrix form: $\overline{\overline{M}}\vec{a} = \vec{b}$

$$\begin{pmatrix} 2 & 4 & -2 \\ 4 & 9 & -3 \\ -2 & -3 & 7 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 8 \\ 10 \end{pmatrix} \quad (4)$$

- Augmented Matrix, $\overline{\overline{M}}\vec{a} = \vec{b} \Rightarrow [\overline{\overline{M}} | \vec{b}]$.

$$\left(\begin{array}{ccc|c} 2 & 4 & -2 & 2 \\ 4 & 9 & -3 & 8 \\ -2 & -3 & 7 & 10 \end{array} \right) \quad (5)$$

- Rules for systems of linear equations: $\overline{\overline{P}}\overline{\overline{D}}\overline{\overline{E}}$

1. Scalar Multiplication, Diagonalized Matrix, ex, $\overline{\overline{D}} = \begin{bmatrix} a & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$,

2. Elimination, Elimination Matrix, ex, $\overline{\overline{E}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -l & 0 & 1 \end{bmatrix}$

3. Row Exchange, Permutation Matrix, ex, $\overline{\overline{P}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$

- Gauss-Jordan Elimination: $\overline{\overline{P}}\overline{\overline{D}}\overline{\overline{E}}\overline{\overline{M}}$

$$\left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 1 & 2 \end{array} \right) \quad (6)$$

- Echelon (Trapezoid) Matrix Form:

- Pivot: the **First non-zero** in the row that does the elimination, p_i .

- Breakdown of Elimination: pivot is zero, $\exists p_i = 0$

- Number of Pivots: # called as the *rank* of a Matrix

- Inverse Matrix, $\overline{\overline{M}}^{-1}$

- LU Decomposition:

- Matrix Operations:

– Commutative:	$\overline{\overline{A}} + \overline{\overline{B}}$;	$\overline{\overline{A}} \cdot \overline{\overline{B}}$	
– Associative:	$\overline{\overline{A}} + (\overline{\overline{B}} + \overline{\overline{C}})$;	$\overline{\overline{A}} \cdot (\overline{\overline{B}} \cdot \overline{\overline{C}})$	
– distributive:	$c(\overline{\overline{A}} + \overline{\overline{B}})$;	$\overline{\overline{C}}(\overline{\overline{A}} + \overline{\overline{B}})$;
– Commutator:	$[\overline{\overline{A}}, \overline{\overline{B}}]$			$(\overline{\overline{A}} + \overline{\overline{B}})\overline{\overline{C}}$

- Span: $\text{span}(S)$

- Generating Set: $\text{span}(S) = \mathcal{V}$

- Linearly Dependent :

- Linearly Independent : $a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_n \vec{v}_n = 0$ iff $a_1 = a_2 = \dots = a_n = 0$ (trivial solution).

- Basis: Linearly Independent \cap Generating Set