

# Lecture 9

## Newton's Method

Jinn-Liang Liu  
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Newton's method is a method for finding successively approximations to a root (*unknown solution*)  $x^*$  of a nonlinear equation

$$g(x) = 0. \quad (9.1)$$

We first choose an initial guess  $x^{(0)}$  that is sufficiently close to  $x^*$  and then determine the tangent line to the curve of  $g(x)$  at the point  $(x^{(0)}, g(x^{(0)}))$  with the slope of  $g'(x^{(0)})$ . This line intercepts the  $x$ -axis at  $x^{(1)}$  which is expected to be closer to  $x^*$  than  $x^{(0)}$ . Then we have another tangent line through  $(x^{(1)}, g(x^{(1)}))$  and obtain  $x^{(2)}$  and so on. In other words, we are iteratively solving the following linearized equation

$$g'(x^{(0)})w = g(x^{(0)}), \quad w = x^{(0)} - x^{(1)}, \quad (9.2a)$$

$$g'(x^{(0)})w = \lim_{t \rightarrow 0} \frac{g(x^{(0)} + tw) - g(x^{(0)})}{t}, \quad \text{or}$$
$$-g'(x^{(0)})x^{(1)} = -g'(x^{(0)})x^{(0)} + g(x^{(0)}) \quad (9.2b)$$

where  $x^{(1)}$  is next iterate (unknown) to be solved then  $x^{(2)}$  (with  $x^{(0)}$  replaced by  $x^{(1)}$ ) and so on. Newton's method thus generates a sequence of approximate solutions  $\{x^{(n)}\}_{n=0}^{\infty}$  to the exact solution  $x^*$ . Three main questions concerning with this method are:

(1) How do we guarantee the convergence, i.e.,  $\lim_{n \rightarrow \infty} x^{(n)} = x^*$  with what initial guess  $x^{(0)}$ ?

(2) How fast is the convergence? (Answer: The convergence order is two (quadratic convergence) if the sequence converges.)

(3) How do we generalize this idea to a nonlinear PDE? This lecture is concerned with this question.

**Question 9.1.** What is linearity? For  $f_1(x) = x$ ,  $f_2(x) = x^2$ ,  $f_3(x) = e^x$ ,  $f_4(X) = AX$  with  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ ,  $X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ ,  $f_5(u) = \frac{du(x)}{dx}$ ,  $f_6(u) = u \frac{du}{dx}$ ,  $f_7(u) = -\frac{d^2u}{dx^2}$ ,  $f_8(u) = \int u(x)dx$ , which one is linear?

**HW 9.1.** Read Newton's method from, for example, Wikipedia and prove (1) and (2).

**Example 9.1.** Consider first the nonlinear equation

$$ax = e^x =: f(x) \quad (9.3)$$

where  $a \neq 0$  is a scalar. Here, we can think  $a$  as a linear operator acting on  $x$ . Then

$$g(x) = ax - f(x) = 0, \quad g'(x) = a - f'(x) = a - e^x \quad (9.4)$$

$$g'(x^{(0)}) = \frac{g(x^{(0)}) - 0}{x^{(0)} - x^{(1)}} \quad (9.5)$$

$$g'(x^{(0)})w = g(x^{(0)}), \quad w = x^{(0)} - x^{(1)}, \text{ or} \quad (9.6a)$$

$$[a - f'(x^{(0)})] x^{(1)} = -f'(x^{(0)})x^{(0)} + f(x^{(0)}), \quad (9.6b)$$

where the last equation is a linearized equation.

**Example 9.2.** We next consider the following coupled nonlinear system with two *unknown solutions* (independent variables)  $(x_1, x_2)$ , the linear operator  $A$  (a matrix), and two nonlinear functions  $f_1(x_1, x_2)$  and  $f_2(x_1, x_2)$ ,

$$\begin{cases} a_{11}x_1 + a_{12}x_2 = f_1(x_1, x_2) \\ a_{21}x_1 + a_{22}x_2 = f_2(x_1, x_2) \end{cases} \quad (9.7)$$

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{bmatrix} \quad (9.8)$$

$$AX = F(X), \quad G(X) = AX - F(X) = 0 \quad (9.9)$$

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}, \quad X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad F(X) = \begin{bmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{bmatrix}$$

$$F'(X) := J(X) = J(x_1, x_2) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix} \quad (\text{Jacobian operator}) \quad (9.10)$$

$$G'(X) = A - F'(X) \quad (9.11)$$

$$G'(X^{(0)})W = G(X^{(0)}), \quad W = X^{(0)} - X^{(1)}, \text{ or} \quad (9.12a)$$

$$[A - F'(X^{(0)})] X^{(1)} = -F'(X^{(0)})X^{(0)} + F(X^{(0)}), \quad (9.12b)$$

**HW 9.2.** Prove (9.12a) using (9.2a). Write (9.12b) explicitly in a system of two linear equations.

**Example 9.3.** This last example is an elliptic semilinear (nonlinear) PDE with now an *unknown solution*  $u(x)$ , the positive linear operator  $-\frac{d^2}{dx^2}$  (acting on ?), and the nonlinear functional (a function of a function)  $f(u)$ ,

$$-u''(x) = f(u) = e^u \quad (9.13)$$

$$G(u) = -u''(x) - f(u) = 0 \quad (9.14)$$

$$\begin{aligned} G'(u)w & : = \lim_{t \rightarrow 0} \frac{G(u+tw) - G(u)}{t} \quad (G'(u) \text{ is an operator}) \quad (9.15a) \\ & = \lim_{t \rightarrow 0} \frac{[-u''(x) - tw'' - f(u+tw)] - [-u''(x) - f(u)]}{t} \\ & = -w'' - \lim_{t \rightarrow 0} \frac{f(u+tw) - f(u)}{t} \\ & = -w'' - \lim_{t \rightarrow 0} \frac{f(u+tw) - f(u)}{tw} w \\ & = -w'' - f'(u)w \quad (9.15b) \end{aligned}$$

Note that the differentiations in  $w''$  and  $f'(u)$  are different, i.e.,  $w' = \frac{dw(x)}{dx}$  and  $f'(u) = \frac{df(u)}{du}$  etc. The linearized problem of (9.13) is thus

$$G'(u^{(0)})w = -w'' - f'(u^{(0)})w = G(u^{(0)}), \quad w = u^{(0)} - u^{(1)} \quad (9.16)$$

If (9.16) is discretized by, for example, the finite difference method (FDM), we obtain a linear system like (9.12) as

$$G'(U^{(0)})W = G(U^{(0)}), \quad W = U^{(0)} - U^{(1)} \quad (9.17a)$$

$$[A - F'(U^{(0)})]U^{(1)} = -F'(U^{(0)})U^{(0)} + F(U^{(0)}) \quad (9.17b)$$

where  $G'(U^{(0)}) = A - F'(U^{(0)})$ ,  $A$  is a coefficient matrix corresponding to the discretization of  $-w''$ ,  $W = [W_1, \dots, W_N]^T$ ,  $F'(U^{(0)})$  is a diagonal matrix with entries  $d_i = f'(U^{(0)}(x_i))$  with  $U^{(0)}(x_i) =: U_i^{(0)} \approx u(x_i)$ ,  $U^{(0)} = [U_1^{(0)}, \dots, U_N^{(0)}]^T$ ,  $G(U^{(0)}) = AU^{(0)} - F(U^{(0)})$ , and  $F(U^{(0)}) = [f(U_1^{(0)}), \dots, f(U_N^{(0)})]^T$ .

The monotone iterative method with FDM for (9.13) is to replace (9.18) by a more general form

$$[A - D]U^{(1)} = -DU^{(0)} + F(U^{(0)}) \quad (9.18)$$

where the matrix  $D$  can be a constant diagonal matrix or a variable diagonal matrix. Of course if  $D = F'(U^{(0)})$ , we have Newton's method.

**Project 9.1.** Consider the following 1D nonlinear Poisson problem

$$-u''(x) = \lambda e^u, \quad \forall x \in (0, 1) \quad (9.19a)$$

$$u(0) = u(1) = 0 \quad (9.19b)$$

where the exact solution  $u(x) = \ln [\cosh^2(\frac{\mu}{2}) \cdot \cosh^{-2}(\mu(x - \frac{1}{2}))]$ ,  $\mu = 2$ ,  $\lambda = 2\mu^2 \cosh^{-2}(\frac{\mu}{2})$ , and  $\cosh(\theta) = \frac{e^\theta + e^{-\theta}}{2}$ . Implement the central finite difference method, the conjugate gradient method, and Newton's method (NM) to find approximate solutions  $U(x)$  to  $u(x)$ . Given a total number of nodes  $N$ , the mesh size  $\Delta x = h = \frac{1}{N-1}$ . The maximum error of an approximate solution  $U(x)$  is defined as

$$\begin{aligned} E^u &= \|e(x)\|_\infty = \|u(x) - U(x)\|_\infty \\ &= \max_{1 \leq i \leq N} |e_i| = \max_{1 \leq i \leq N} |u_i - U_i|. \end{aligned} \quad (9.20)$$

Example: For  $N = 5$ , we have  $h = \frac{1}{4}$  and

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ \frac{-1}{h^2} & \frac{2}{h^2} & \frac{-1}{h^2} & 0 & 0 \\ 0 & \frac{-1}{h^2} & \frac{2}{h^2} & \frac{-1}{h^2} & 0 \\ 0 & 0 & \frac{-1}{h^2} & \frac{2}{h^2} & \frac{-1}{h^2} \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \quad (\text{See (1.17)}), \quad (9.21)$$

$$\begin{aligned} U^{(0)} &= \begin{bmatrix} U_1^{(0)} \\ U_2^{(0)} \\ U_3^{(0)} \\ U_4^{(0)} \\ U_5^{(0)} \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{1}{4} \\ \frac{1}{2} \\ \frac{3}{4} \\ 0 \end{bmatrix} \quad \text{or} \quad = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{1}{4} \\ \frac{1}{2} \\ \frac{3}{4} \\ 1 \end{bmatrix}, \\ \vec{u} &= \begin{bmatrix} u_1 = u(x_1) \\ u_2 = u(x_2) \\ u_3 = u(x_3) \\ u_4 = u(x_4) \\ u_5 = u(x_5) \end{bmatrix} \end{aligned} \quad (9.22)$$

$$D = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & d_2 & 0 & 0 & 0 \\ 0 & 0 & d_3 & 0 & 0 \\ 0 & 0 & 0 & d_4 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix},$$

$$d_2 = f'(U^{(0)}(x_2)) = \lambda e^{U^{(0)}(x_2)} = \lambda e^{U_2^{(0)}} = \lambda e^{\frac{1}{4}} \quad (9.23)$$

$$F(U^{(0)}) = \begin{bmatrix} 0 \\ F_2 \\ F_3 \\ F_4 \\ 0 \end{bmatrix},$$

$$F_2 = f(U^{(0)}(x_2)) = \lambda e^{U^{(0)}(x_2)} = \lambda e^{U_2^{(0)}} = \lambda e^{\frac{1}{4}} = d_2 \quad (9.24)$$

$$[A - D]U^{(1)} = -DU^{(0)} + F(U^{(0)}) \quad \implies \quad \widehat{A}U^{(1)} = \vec{b} \quad (9.25)$$

$$\widehat{A} = A - D, \quad \vec{b} = \begin{bmatrix} 0 \\ b_2 \\ b_3 \\ b_4 \\ 0 \end{bmatrix}, \quad b_2 = -d_2 U_2^{(0)} + d_2 \quad (9.26)$$

**Algorithm NM: Newton's Method** Find approximate solution  $U(x)$  of (9.19).

**Input:**  $N, l \max, EUTol$ .

**Step 1.** Set  $A, U^{(0)}, \vec{x}$  in (9.21) and (9.22).

**Step 2.** Set the exact solution  $\vec{u}$  in (9.22).

**Step 3.** For  $l = 1, \dots, l \max$ , do Step 4-8. (Newton's iteration.)

**Step 4.** Set the diagonal matrix (vector)  $D$  in (9.23).

**Step 5.** Set  $\widehat{A}$  and  $\vec{b}$  in (9.25).

**Step 6.** Call CG or SOR or JM to solve  $\widehat{A} U^{(1)} = \vec{b}$ .

**Step 7.** Compute  $EU = \max_{1 \leq i \leq N} |U_i^{(1)} - U_i^{(0)}|$ .

**Step 8.** If  $EU < EUTol$  then compute  $E^u = \max_{1 \leq i \leq N} |u_i - U_i^{(1)}|$  and stop, else set  $U^{(0)} = U^{(1)}$  and go to Step 3.

**Output:**

$N$	$l$	$E^u$
5		
9		
17		
33		
65		
129		

**Question 9.2.** (1) Verify the exact solution satisfy (9.19). (2) Write (9.17b) explicitly in a system of five linear equations for the problem in Project 9.1, i.e.,  $N = 5$ . (3) How do you choose an initial guess for Newton's method in your program?

**HW 9.3.** Can you show numerically the quadratic convergence by your program? Answer this question by writing the mathematical formulas before programming.

**HW 9.4.** Use (9.15a) as the definition of the operator  $G'(u)w$  to prove that (a)  $g'(x^{(0)})w = [a - f'(x^{(0)})]w$  in (9.2) with  $u = x^{(0)}$  and  $G'(u) = g'(x^{(0)})$ , (b)  $G'(X^{(0)})W = [A - F'(X^{(0)})]W$  in (9.12) with  $u = X^{(0)}$  and  $G'(u) = G'(X^{(0)})$ .