# Note for Quantum Optics: Uncertainty Relation

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(Dated: Spring, 2021)

Reference:

Ch. 1-5 in P. Dirac "The Principles of Quantum Mechanics," Oxford University Press (1958). Chapter 2, in J. J. Sakurai, "Modern Quantum Mechanics," Addison Wesley (1994).

#### I. UNCERTAINTY RELATION

- 1. Non-commuting observable do not admit common eigenvectors.
- 2. Non-commuting observables can not have definite values simultaneously.
- 3. Simultaneous measurement of non-commuting observables to an arbitrary degree of accuracy is thus incompatible.
- 4. Variance: one can define

$$\Delta \hat{A}^2 = \langle \Psi | (\hat{A} - \langle \hat{A} \rangle)^2 | \Psi \rangle = \langle \Psi | \hat{A}^2 | \Psi \rangle - \langle \Psi | \hat{A} | \Psi \rangle^2. \tag{1}$$

5. For any two non-commuting observables,

$$[\hat{A}, \hat{B}] = i\hat{C},$$

we have the *uncertainty relation*:

$$\Delta A^2 \Delta B^2 \ge \frac{1}{4} [\langle \hat{F} \rangle^2 + \langle \hat{C} \rangle^2], \tag{2}$$

where

$$\hat{F} = \hat{A}\hat{B} + \hat{B}\hat{A} - 2\langle \hat{A}\rangle\langle \hat{B}\rangle,\tag{3}$$

where the operator  $\hat{F}$  is a measure of correlations between  $\hat{A}$  and  $\hat{B}$ .

For example, take the operators  $\hat{A} = \hat{q}$  (position) and  $\hat{B} = \hat{p}$  (momentum) for a free particle, one have

$$[\hat{q}, \hat{p}] = i\hbar \to \langle \Delta \hat{q}^2 \rangle \langle \Delta \hat{p}^2 \rangle \ge \frac{\hbar^2}{4}. \tag{4}$$

### A. Proof of the Uncertainty Relation

Start from the Schwarz inequality

$$\langle \phi | \phi \rangle \langle \psi | \psi \rangle \ge \langle \phi | \psi \rangle \langle \psi | \phi \rangle, \tag{5}$$

where the equality holds if and only if the two states are linear dependent,  $|\psi\rangle = \lambda |\phi\rangle$ , where  $\lambda$  is a complex number. Define two states,

$$|\psi_1\rangle = [\hat{A} - \langle \hat{A} \rangle]|\psi\rangle, \tag{6}$$

$$|\psi_2\rangle = [\hat{B} - \langle \hat{B} \rangle]|\psi\rangle. \tag{7}$$

To have a minimum value of the uncertainty product, we have  $|\psi_1\rangle = -i\lambda |\psi_2\rangle$ , or

$$[\hat{A} + i\lambda \hat{B}]|\psi\rangle = [\langle \hat{A} \rangle + i\lambda \langle \hat{B} \rangle]|\psi\rangle = z|\psi\rangle, \tag{8}$$

where z is a complex number. And the state  $|\psi\rangle$  is called a minimum uncertainty state. There are difference values for the coefficient  $\lambda$ ,

1. If  $Re(\lambda) = 0$ , then  $\hat{A} + i\lambda \hat{B}$  is a normal operator, which have orthonormal eigenstates, with the

$$\Delta \hat{A}^2 = -\frac{i\lambda}{2} [\langle \hat{F} \rangle + i \langle \hat{C} \rangle], \tag{9}$$

$$\Delta \hat{B}^2 = -\frac{i}{2\lambda} [\langle \hat{F} \rangle - i \langle \hat{C} \rangle]. \tag{10}$$

2. If we set  $\lambda = \lambda_r + i\lambda_i$ , then

$$\Delta \hat{A}^2 = \frac{1}{2} [\lambda_i \langle \hat{F} \rangle + \lambda_r \langle \hat{C} \rangle], \tag{11}$$

$$\Delta \hat{B}^2 = \frac{1}{|\lambda|^2} \Delta \hat{A}^2, \tag{12}$$

along with the condition that

$$\lambda_i \langle \hat{C} \rangle - \lambda_r \langle \hat{F} \rangle = 0. \tag{13}$$

• If  $|\lambda| = 1$ , we have

$$\Delta \hat{A}^2 = \Delta \hat{B}^2,\tag{14}$$

which are equal variance minimum uncertainty states.

• If  $|\lambda| = 1$  along with  $\lambda_i = 0$ , we have

$$\Delta \hat{A}^2 = \Delta \hat{B}^2$$
 and  $\langle \hat{F} \rangle = 0$ , (15)

which are uncorrelated equal variance minimum uncertainty states.

• If  $\lambda_r \neq 0$ , we have

$$\langle \hat{F} \rangle = \frac{\lambda_i}{\lambda_n} \langle \hat{C} \rangle, \tag{16}$$

$$\Delta \hat{A}^2 = \frac{|\lambda|^2}{2\lambda_r} \langle \hat{C} \rangle, \tag{17}$$

$$\Delta \hat{B}^2 = \frac{1}{2\lambda_r} \langle \hat{C} \rangle. \tag{18}$$

If  $\hat{C}$  is a positive operator then the minimum uncertainty states exist only if  $\lambda_r > 0$ .

## II. UNCERTAINTY RELATION FOR $\hat{q}$ AND $\hat{p}$

Take the operators  $\hat{A} = \hat{q}$  (position) and  $\hat{B} = \hat{p}$  (momentum) for a free particle, then we have

$$[\hat{q}, \hat{p}] = i\hbar \to \langle \Delta \hat{q}^2 \rangle \langle \Delta \hat{p}^2 \rangle \ge \frac{\hbar^2}{4}.$$
(19)

If we define two states,

$$|\psi_1\rangle = [\hat{A} - \langle \hat{A} \rangle] |\psi\rangle \equiv \hat{\alpha} |\psi\rangle,$$
 (20)

$$|\psi_2\rangle = [\hat{B} - \langle \hat{B} \rangle] |\psi\rangle \equiv \hat{\beta} |\psi\rangle.$$
 (21)

For  $uncorrelated\ minimum\ uncertainty\ states,$  one has

$$\hat{\alpha}|\psi\rangle = -i\lambda\hat{\beta}|\psi\rangle, \qquad \langle\psi|\hat{\alpha}\hat{\beta} + \hat{\beta}\hat{\alpha}|\psi\rangle = 0,$$
 (22)

where  $\lambda$  is a real number. If  $\hat{A} = \hat{q}$  and  $\hat{B} = \hat{p}$ , we have

$$(\hat{q} - \langle \hat{q} \rangle) |\psi\rangle = -i\lambda(\hat{p} - \langle \hat{p} \rangle) |\psi\rangle. \tag{23}$$

By defining the complex number

$$\lambda = e^{-2r},\tag{24}$$

then

$$(e^{r}\hat{q} + ie^{-r}\hat{p})|\psi\rangle = (e^{r}\langle\hat{q}\rangle + ie^{-r}\langle\hat{p}\rangle)|\psi\rangle. \tag{25}$$

To have the minimum uncertainty state, we define it as an eigenstate of a non-Hermitian operator:

$$e^r \hat{q} + i e^{-r} \hat{p}, \tag{26}$$

with a c-number eigenvalue  $e^r\langle \hat{q} \rangle + i e^{-r} \langle \hat{p} \rangle$ , and the corresponding variances of  $\hat{q}$  and  $\hat{p}$  are

$$\langle \Delta \hat{q}^2 \rangle = \frac{\hbar}{2} e^{-2r}, \tag{27}$$

$$\langle \Delta \hat{p}^2 \rangle = \frac{\hbar}{2} e^{2r}, \tag{28}$$

here r is referred as the *squeezing parameter*.

#### III. GAUSSIAN WAVE PACKETS

In the x-space, we have a Gaussian wave packet with the form,

$$\Psi(x) = \langle x | \Psi \rangle = \left[ \frac{1}{\pi^{1/4} \sqrt{d}} \right] \exp\left[ikx - \frac{x^2}{2d^2}\right],\tag{29}$$

which is a plane wave with wave number k and width d. The expectation value of  $\hat{X}$  is zero due to the symmetry, *i.e.*,

$$\langle \hat{X} \rangle = \int_{-\infty}^{\infty} \mathrm{d}x \langle \Psi | x \rangle \hat{X} \langle x | \Psi \rangle = 0,$$

where the variation of  $\hat{X}$  is

$$\langle \Delta \hat{X}^2 \rangle = \frac{d^2}{2}.\tag{30}$$

In the *p*-space, the expectation value of  $\hat{P}$  is  $\langle \hat{P} \rangle = \hbar k$ , *i.e.*,

$$\langle x|\hat{P}|\Psi\rangle = -i\hbar \frac{\partial}{\partial x} \langle x|\Psi\rangle,$$
 (31)

while the variation of  $\hat{P}$  is

$$\langle \Delta \hat{P}^2 \rangle = \frac{\hbar^2}{2d^2}.\tag{32}$$

The Heisenberg uncertainty product for a Gaussian wave packet is

$$\langle \Delta \hat{X}^2 \rangle \langle \Delta \hat{P}^2 \rangle = \frac{\hbar^2}{4}.$$
 (33)

A Gaussian wave packet is called a minimum uncertainty wave packet.

### IV. TIME EVOLUTION OF A MINIMUM UNCERTAINTY STATE

For a free particle, the corresponding Hamiltonian is

$$\hat{H} = \frac{\hat{p}^2}{2m},\tag{34}$$

with the unitary operator

$$\hat{U} = \exp(-\frac{i}{\hbar} \frac{\hat{p}^2}{2m} t). \tag{35}$$

In the Schrödinger picture, the wave function evolves accordingly

$$\Psi(q,t) = \langle q|\hat{U}|\Psi(0)\rangle = \int_{-\infty}^{\infty} dp \langle |p\rangle \Psi(p,0) \exp(-\frac{i}{\hbar} \frac{p^2}{2m} t), \tag{36}$$

$$= \frac{1}{(2\pi)^{1/4}(\Delta q + i\hbar t/2m\Delta q)^{1/2}} \exp\left[-\frac{q^2}{4(\Delta q)^2 + 2i\hbar t/m}\right],\tag{37}$$

where the variance in x(q)0-space is defined as

$$\Delta q = \hbar/2\langle \hat{p}^2 \rangle^{1/2}. \tag{38}$$

It can be shown that even though the momentum uncertainty  $\langle \Delta \hat{p}^2 \rangle$  is preserved, but the position uncertainty increases as time develops,

$$\langle \Delta \hat{q}^2(t) \rangle = (\Delta \hat{q})^2 + \frac{\hbar^2 t^2}{4m^2 (\Delta q)^2}.$$
 (39)

This is known as the *free particle expansion*.

## V. GAUSSIAN OPTICS

In free space, the vector potential, A, is defined as  $A(r,t) = \vec{n}\psi(x,y,z)e^{j\omega t}$ , which obeys the vector wave equation,

$$\nabla^2 \psi + k^2 \psi = 0. \tag{40}$$

With the paraxial wave approximation,  $\psi(x,y,z) = u(x,y,z)e^{-jkz}$ , one obtains

$$\nabla_T^2 u - 2jk \frac{\partial u}{\partial z} = 0, \tag{41}$$

where  $\nabla_T \equiv \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y}$ . The solution of the scalar paraxial wave equation is,

$$u_{00}(x,y,z) = \frac{\sqrt{2}}{\sqrt{\pi w}} exp(j\phi) exp(-\frac{x^2 + y^2}{w^2}) exp[-\frac{jk}{2R}(x^2 + y^2)], \tag{42}$$

which is also a Gaussian wave packet.